

PROtronic BaseLINE

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Variant UCU-FS (Universal Control Unit for Functional Safety)



As with series control units, a powerful microcontroller of the type NXP MPC5554 is used as a real-time computer unit in the **PROtronic BaseLINE**. As with the *TopLINE*, state-of-the-art FPGA technology is used to assist the microcontroller in computing-intensive peripheral tasks and ensure the required flexibility for the inputs and outputs. Due to the compact housing and the low starting price the **PROtronic BaseLINE** is the ideal solution for fleet tests and cost-sensitive applications.

Basic System	
Operating Voltage:	6.5 V ... 32 V DC
Temperature Range:	-40 °C ... +85 °C housing temperature
Electrical Strength:	Short-circuit against Ground and V _{Bat} for all power supply terminals Power switches are also protected against overload
Mechanical Stress:	Vibration and temperature testing according to DIN ISO 16750-3 Part 4.1.3.1.5.2, DIN EN 60068-2-64
IP code (EN 60529):	IP64K
EMV Stability:	Interference emission/reception tests, CE conformal
External Connector:	2 x 70-pin (AMP)
Housing:	Aluminium, (W x H x L) 280 mm x 63 mm x 196 mm
Weight:	3.4 kg

CPU	
Processor:	MPC5554 (120 MHz, Floating-Point-Unit)
Memory:	Flash: 2 MByte (µController internal) 8 MByte (µController external) RAM: 4 MByte external (64 KByte µController internal) EEPROM: 32 KByte (µController external)
Debug Interface:	JTAG and NEXUS via adaptor box ¹⁾
I/O-Processor:	Automotive FPGA (for time and crank-angle synchronous control of the actuators / sensor analysis)

Communication Interfaces	
CAN:	2 x CAN 2.0 B Full-CAN Transceiver (High-Speed, 1 MBaud max. / ISO DIS 11898)
LIN (available as an option) ^{1) 2)} :	2 x LIN, according to LIN specification 1.3, 2.0, 2.1, 2.2 Configurable as LIN-Master or LIN-Slave
SENT ⁵⁾ :	6 x SENT, according to SENT specification SAE J2716 Configurable in groups of 3 as SENT-Master or SENT-Slave

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Analog Inputs	
Number:	24, 4 groups each with 6 channels Standard hardware set-up: 6 x: $U = 0 \dots 10.14 \text{ V}$, $f_c = 14 \text{ kHz}$, typical application: load amplifier, pressure sensor 2 x: $U = 0 \dots 10.14 \text{ V}$, $f_c = 1.4 \text{ kHz}$, typical application: pressure sensor, active sensors 6 x: $U = 0 \dots 5.07 \text{ V}$, $f_c = 0.7 \text{ kHz}$, typical application: pressure sensor, active sensors 6 x: $U = 0 \dots 5.07 \text{ V}$, $f_c = 0.7 \text{ kHz}$, typical application: temperature sensor 4 x: $U = 0 \dots 5.07 \text{ V}$, $f_c = 0.7 \text{ kHz}$, typical application: potentiometer, positional sensor
Resolution:	12 Bit
Input Voltage:	Uni-polar or bi-polar (depending on hardware set-up)
Input Filter (analog):	Low-pass 1st order, cut-off frequency can be set via hardware set-up
Input Filter (digital):	Low-pass 1st order, cut-off frequency configurable
Dynamic Behaviour:	Sampling rate per channel: $> 100 \text{ kHz}$
Signal Types:	<ul style="list-style-type: none"> ■ Analog input ■ Digital input (with programmable threshold and hysteresis)
Sensor Supply:	Per group: $0 \text{ V} \dots V_{\text{Bat}} / 100 \text{ mA}$

Analog Outputs, alternative³⁾ to Analog Input Group 4	
Number:	6, one group with 6 channels
Resolution:	12 Bit
Output Voltage:	$0 \dots 10 \text{ V}/\text{max. } 10 \text{ mA}$
Dynamic Behaviour:	Update rate: 70 kHz

Crankshaft Inputs	
Number:	2 x hall sensor input: measurement range $0 \dots 5.06 \text{ V}$, $f_c = 66 \text{ kHz}$ 2 x inductive sensor input: measurement range $-29.9 \dots + 29.9 \text{ V}$, $f_c = 16 \text{ kHz}$ Common sensor voltage Further inputs for processing of crank circuit signals available for fast digital inputs / outputs.
Operating Range:	Engine speed $50 \dots 12000 \text{ rpm}^{4)}$
Crankshaft Tooth System:	Configurable, 36 – 3600 teeth with 1 to 4 gaps or one additional tooth, e.g. 36 ± 1 , $60-(1\dots 4)$, $60-1-1$ (symmetrically), 360 increments / revs, 3600 increments / revs, etc.
Camshaft Tooth System:	Configurable, 1 to 15 teeth
Resolution:	$0.1 \text{ } ^\circ\text{KW}$
Sensor Type:	Inductive or hall
Dynamic Behavior:	Sampling rate per channel: 500 kHz
Sensor Supply:	$0 \text{ V} \dots V_{\text{Bat}} / 100 \text{ mA}$

Fast Digital Inputs / Outputs	
Number:	12, 2 groups each with 6 channels, in groups as input / output configurable
Input:	5 ... 32 V, threshold configurable group-wise Standard equipment: 24.8 k Ω , pull-down
Output:	Push/pull output 75 Ω
Input signal types:	<ul style="list-style-type: none"> ■ Digital input ■ Pulse and frequency measurement input ■ Event generation at edge change input
Output signal types:	<ul style="list-style-type: none"> ■ Digital output ■ PWM output

Power Switch Outputs	
Number:	24, 4 groups with 6 channels each
Supply:	Per group, 6.5 ... 52 V external
Output:	Push/pull, low side or high side output 5 A, 11 A peak Parallel switching of up to 6 channels possible Load capacity of supply: max. 20 A per group
Signal Types:	<ul style="list-style-type: none"> ■ Digital output ■ PWM output, 20 Hz ... 10 kHz ■ Full bridge output, 20 Hz ... 10 kHz ■ Peak & Hold output, 20 Hz ... 10 kHz ■ Peak & Hold current measurement ■ Pulse output (angle-synchronous) ■ Ignition output (control of external power stages), max. 20 ms ■ Current controlled output

Ignition Outputs	
Number:	6, one group with 6 channels for control of an external ignition power stage Diagnosis functions of external ignition power stage
Output:	0 ... 4.6 V, push/pull voltage output or 8 ... 25 mA power output, max. 16 V
Signal Types:	Ignition Control

¹⁾ Additional hardware module required.

²⁾ Additional software required (LIN ACI-Blockset).

³⁾ Not included in standard version.

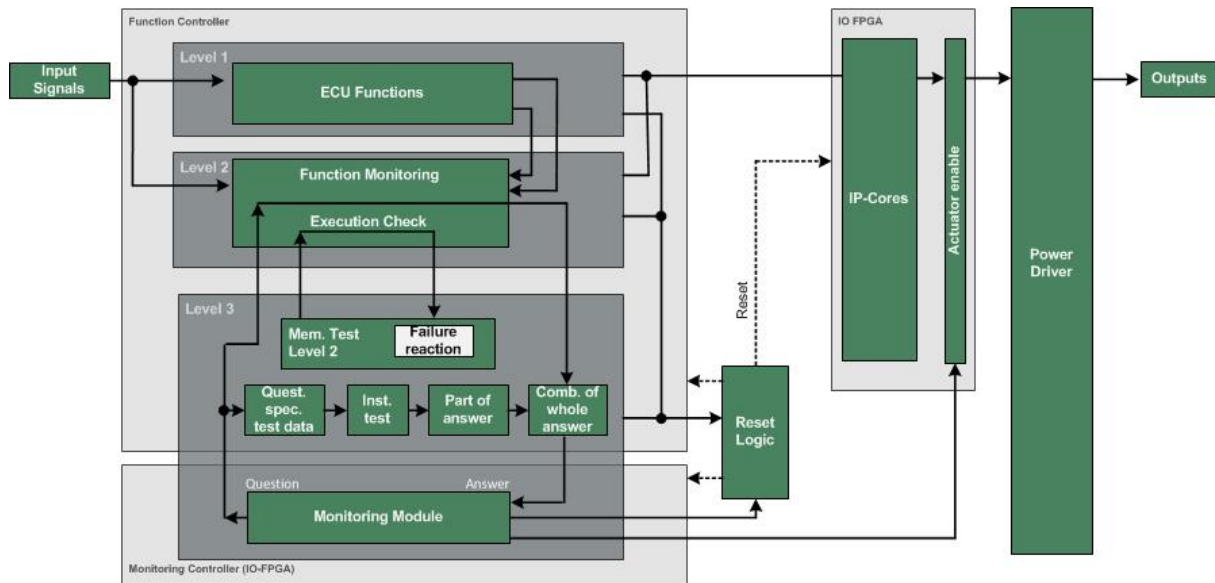
⁴⁾ For incremental sensors, a lower maximum rev. speed applies depending on the number of teeth.

⁵⁾ While using the SENT interface the fast digital I/O groups will be reduced by one.

Functional Safety Concept of **PROtronic** TopLINE UCU-FS

The functional safety concept of the **PROtronic** TopLINE UCU-FS consists of two main parts:

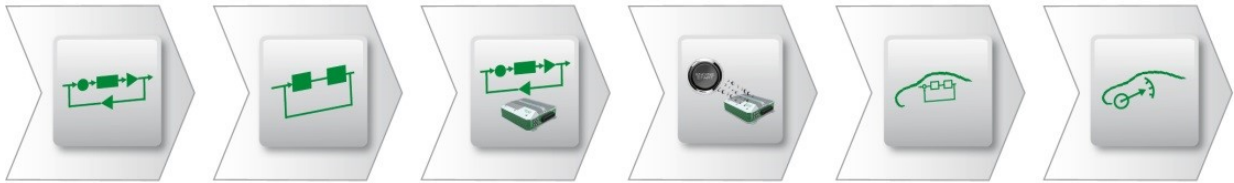
1. A multilevel monitoring concept for developing application-specific safety functions in the **PROtronic** control unit.



Overview Safety Concept:

- Main CPU runtime monitoring with independent safety processor
- Freely programmable monitoring level (level 2) to verify correct execution of main software
- Enforcement of defined state of inputs and outputs on detected faults
- Configurable shut-down trigger option from desired software level, to ensure a safe state of system on detected faults
- Monitoring of functional code execution
- Monitoring of runtime response and instruction code test
- Monitoring and diagnostics of system integrity and supply voltages
- Extensive diagnostics functions of the inputs and outputs
- Initial and cyclic check of system memory (RAM, code and data segments)
- System-watchdog
- Integrated fault detection and fault memory functionality
- Max. number of re-start trials configurable by user
- Option to switch off the safety functions for development and test purpose

Development Environment



Smooth transition from design to mass production

The development environment of the **PROtronic TopLINE** is based on tools that are widespread in the automotive industry. It not only offers free scope when choosing the code generator but also for measurement and calibration tools.

1 Model-based software development

- Graphical modeling of control functions with MATLAB®, Simulink® and Stateflow®.

2 Offline simulation

- Testing and optimisation of the functional design against a plant design using offline simulation on the PC with MATLAB®, Simulink® and Stateflow®.

3 Hardware mapping

- Mapping and configuration of the control functions in the model to the inputs and outputs of the hardware using a graphic block library based on Simulink® – Application Controller Interface (ACI).

4 Automatic code generation

- Generation of highly efficient production code at the press of a button, alternatively with the code generators TargetLink® or Embedded Coder™.

5 Test and verification

- Downloading the generated software to the control unit with Schaeffler Engineering boot loader tool.
- Testing and verification of the new developed control functions on a test-stand, in the vehicle or via hardware-in-the-loop simulation.

6 Measurement and calibration

- Fine tuning and measurement of the control functions using a measurement and calibration tool, alternatively with **MARC I**, INCA or CANape.